Economic and Social Council

Economic Commission for Europe

Inland Transport Committee

World Forum for Harmonization of Vehicle Regulations

198th session
Geneva, 10–13 March 2026
Item 4.7.9 of the provisional agenda
1958 Agreement:
Consideration of draft amendments to existing
UN Regulations submitted by GRVA

Proposal for Supplement 1 to the 01 series of amendments to UN Regulation No. 130 (LDWS)

Submitted by the Working Party on Automated/Autonomous and Connected Vehicles*

The text reproduced below was adopted by the Working Party on Automated/Autonomous and Connected Vehicles (GRVA) at its twenty-third session (ECE/TRANS/WP.29/GRVA/23, para. 54). It is based on ECE/TRANS/WP.29/GRVA/2025/42. It is submitted to the World Forum for Harmonization of Vehicle Regulations (WP.29) and to the Administrative Committee (AC.1) for consideration and vote at their March 2026 sessions.

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* In accordance with the programme of work of the Inland Transport Committee for 2026 as outlined in proposed programme budget for 2026 (A/80/6 (Sect. 20), table 20.7), the World Forum will develop, harmonize and update UN Regulations in order to enhance the performance of vehicles. The present document is submitted in conformity with that mandate.

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Paragraph 5.3.1., amend to read:

"5.3.1.	The LDWS function shall be automatically reinstated at each initiation of the powertrain[3]. A new engine start (or run cycle) which is performed automatically, e.g. the operation of a stop/start system, shall not be considered an "initiation of the powertrain" wherever that term is used in this Regulation.

Insert new footnote 3, to read:

[3] As defined in Mutual Resolution No. 2 (M.R.2) of the 1958 and the 1998 Agreements containing vehicle propulsion system definitions, see document ECE/TRANS/WP.29/1121.

Paragraph 6.6.2., amend to read:

6.6.2.	The failure warning signal mentioned in paragraph 5.4.2. above shall be activated and remain activated while the vehicle is being driven and be reactivated after each subsequent initiations of the powertrain as long as the simulated failure exists.