Background information for ICCT's proposal to amend the UN Regulation No. 51

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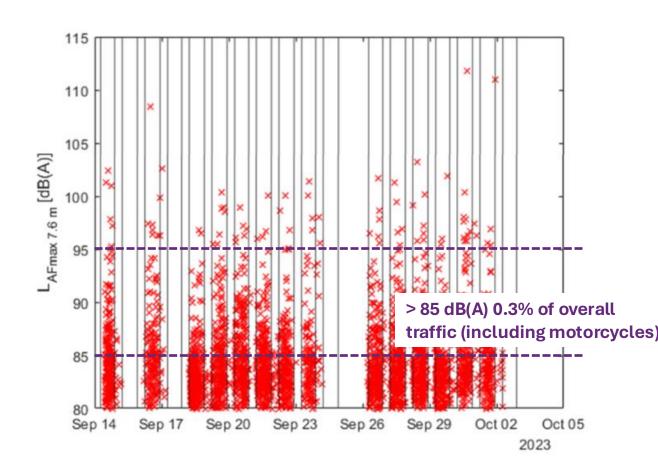


ICCT's Proposal

- Not-To-Exceed (NTE) limits
 - 85 dB(A) at 7.5m within the Annex 7 and Annex 9 control range
 - 95 dB(A) at 7.5m beyond the ASEP and RD-ASEP control range (up to 80 km/h within *Annex 7* and 100 km/h within *Annex 9*) or in real-world operating conditions (for easier enforcement)
- Strengthened defeat device clause to safeguard consistent performance in real-world and testing conditions
- Other suggestions
 - NTE limits for stationary vehicle sounds

Objective 1: Safeguard public health in urban environment by limiting excessive vehicle noise

- An additional uniform maximum sound limit ensures that the vehicles does not emit noise at levels harmful to human health.
- Annoyance, a WHO indicator for measuring adverse health impacts of noise and which accounts for a number of diseases linked to noise, is associated with 95 dB(A).
- 85 dB(A) at 7.5m amplified to > 96 dB(A) at 2m, a distance at which pedestrians in urban environment are exposed to vehicle noises.



Noise camera test in Geneva – Rue de Lyon 50km/h, BAFU (2024)

Objective 2: Enhance efficiency and effectiveness of surveillance and enforcement mechanisms

- A single maximum limit provides clear, technologically neutral and quantifiable benchmark for effective market surveillance and enforcement efforts.
- Use of the ASEP curve (Annex 7) and the expected sound model (Annex 9) is complicated for non-experts.
- Current approach and that in preparation (Annex 7 and Annex 9) set sound emission limit based on parameter among which speed and acceleration.
- Allows non-compliance detection through roadside enforcement, noise radar, or inservice conformity testing.
- Reduces administrative burdens for enforcement authorities.

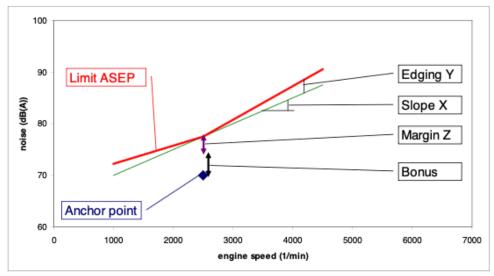


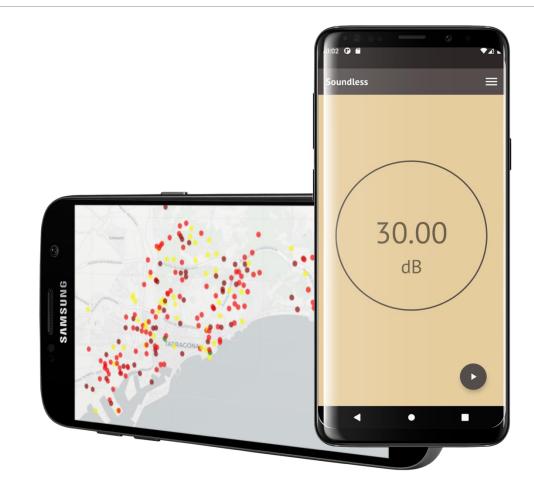
Figure 1: ASEP proposal of the GRBIG; sketch of the limit curve and the different coefficients which determine the stringency.

Kortbeek and de Graaff (2009)

Parameter	Value	Value Unit Mandatory Explanation				CASES (see Annex 9 Appendix)			
Select Parameter SET	A	- CHAN		Select the applicable column A, or B or C from the Parameter table (see 4b)	Parallel	3.2.3.1	3.2.3.2	3.2.3.3.	3.2.3.4
Applicable Column of Parameter Table	1			parent on apparatus countries, or a or C main the Parameter actor (see 40)	Hybrids	1	2	3	4
Applicable Column of Parameter Faces					Sacc Ancien	74	74	73.2	73.2
Necessary Data Evaluation in Cases where no Engine Speed is available in Annex 3 Pass-By Texts)					Micc More	1960.6	1960.6	3667	3667
Hybrid Engine Operation Principle	N	1	a trigon sports	From (1) Vehicle Data: serial (5), parallel (P) or no Hybrid (N)		69.3	69.8	69.3	69.8
Was the ICE operational during ACC Test in Annex 3.7	Y			Mandatory in case of HEV, for ICE and EV selection is ignored	SCHOOL STATE	1782	1389	1782	1389
Was the ICE operational during CRS Test in Annex 3 ?	Y		_	Mandatory in case of HEV, for ICE and EV selection is ignored	NOS ANDIOR	1762	1369	1762	1369
Variety of the state of the sta							CASES Issa A	nnex 9 Appendix)	
Which gear was used for the Acceleration Test Annex 3	2			Choice is mandatory in Case of Hybrids (CASES 3 and 4)	Serial Hybrids	3241	3.2.4.2	3.2.4.3.	3244
Which gear was used for the Acceleration Test Annex 3 Vehicle Speed to Engine Speed Ratio	15.0			Choice is mandatory in Case of Hybrids (CASES 3 and 4)		3.2.4.1	3.2.4.2	3.2.4.3.	3.2.4.4
Which gear was used for the Constant Speed Test Annex 3	5			Choise is mandatory in Case of Hybrids (CASES 2 and 4)		74	74	73.2	73.2
				Choise is mandatory in Case of Hytinds (CASES 2 and 4)	Sec. Mores				
Vehicle Speed to Engine Speed Ratio	36.0		_		Миссионя	1960.6	1960.6	2750	2750
Applicable Values from Arress 3 pages for test if needed, corrected by IMRRID CASE and LOW PMR CONSIDERATIONS					SCHI, MACHINI	69.3	69.8	69.3	69.8
		1	corrected by H	PRITID CASE and LOW PMR CONSIDERATIONS)	NOS, AND IOS	1782	1833	1782	1833
LACC, AND COST	74.0	dB(A)							
Necasor	1961	rpm		Value is selected from the upper table to the right, in case of HEV with a parallel operation principle,			X (Emulation of	constant speed n	
los,wores	69.3	dB(A)		or from the lower table to the right, in case of HEV with a serial operation principle	PMR <25	N		Propulsion type	
Nos,work	1782	rpm			ANNE	X 3 Data		Adjust	ed Data
					Sec, andres	74.0		FACE, AND HER	74.0
			namk (Needed	for Model Consistency)	V _{ACC,ANDIER}	55.0		V _{ACC,ANDIER}	55.0
Check Dynamic L _{CC, ANDION*} L _{CKS, ANDION}	4.7	dB		See Annex 9 Appendix Parahraph 2.7	Мьсс,ичения	1961		Мьсс,инони	1961
Assign minimum dynamic	N				Чень, именен	0.0.		Чень, именен	72.9
					VOIS, AND HOR	0.0.		VONLANDIGH	50.0
Tyre share of the Constant Speed Test (Determined either by Measurement or Standard Value taken from Parameter Table **** CLARIFICATION NEEDED, NO OWEK IF Los June Values						0.0.]	NOS ANDION	1782
Determination of x-factor	M		•	Select from Parameter Table (T) or by Direct Measurement (M)					
Check validity of L _{IX,RD} (when Direct Measurement (M) is selected)	VALID			Check if energy of L _{CE,RGF} is lower than 99% of energy from L _{CELRGF}					
x-factor determined by Direct Measurement (M)	95	%		Determined based on the selection above					
					Gears	Ratios	MaxAcc	1	
Maximum vehicle acceleration determined by discrete tests, which are not part of the RD-ASEP assessment (see Armex 9; Appendix 1; paragraph						8.0	3.48		
Maximum Acceleration determined	2.2	m/s²	•	See provisions of Annex 9 Appendix paragraph 3.6.1.1.	2	15.0	1.86		
Selected gear or range (D) for this test	3		•	Select D(EV) for tests of EV and D(HEV) for HEV in EV mode	3	21.0	1.33		
V _{AK} determined for the test	35.0	km/h	•	Average of the 4 runs of Annex 3, value to be entered to the first decimal	- 4	28.0	1.00		
V _{air} as reported	45.0	km/h		Average of the 4 runs of Annex 3, value to be entered to the first decimal	5	36.0	0.77	1	
	57.0	km/h	•	Average of the 4 runs of Annex 3, value to be entered to the first decimal	6			1	
v _{as} : as reported	1500	1/min		Average of the 4 runs of Annex 3, value to be entered as integer	7				
					-		_	1	
r _{tur} as reported	3200	1/min	•	Average of the 4 runs of Annex 3, value to be entered as integer	8				
V _{Max} as reported thought as reported thought as reported thought as reported	2300	1/min 1/min		Average of the 4 runs of Annex 3, value to be entered as integer Average of the 4 runs of Annex 3, value to be entered as integer	9			1	

Objective 3: Promote transparency and accountability in regulatory processes and industry performance

- Enables citizens, local communities, and other organizations to better understand how the vehicle noise is regulated.
- Empowers citizens to advocate for healthier urban environments and promotes citizen participation in noise monitoring.
- Improves accountability from both regulators and manufacturers



Soundless.app

Paragraph 6.2.3. Defeat device

The vehicle manufacturer shall not intentionally alter, adjust, or introduce any mechanical, electrical, thermal, or other device or procedure solely for the purpose of fulfilling the sound emission requirements as specified under this Regulation. which is not operational during typical on-road operation.

- "Solely for the purpose of fulfilling the sound emission requirements" can permit the use of a device or procedure used not only to meet the requirements but also for other purposes, such as to protect vehicle components or performance.
- "which is not operational during typical on-road operation" allows the use of device in a small subset of conditions prescribed in the type-approval test, which are hardly encountered in real-world driving.

Other suggestions to amend UNR 51

- Annex 9
 - Widened performance range from 35 m²/s³ to 55 m²/s³
 - Expanded engine speed range of a vehicle to 100% of S
- Paragraph 6.2.2.
 - NTE limit of 95 dB(A) for vehicle stationary sounds within the Annex 3 control range
 - NTE limit of 110 dB(A) for vehicle stationary sounds beyond the Annex 3 control range (e.g. snap free acceleration test)

Thank you for your attention!

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