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## Economic Commission for Europe

### Inland Transport Committee

### World Forum for Harmonization of Vehicle Regulations

#### 197th session

Geneva, 11–14 November 2025

Item 4.10.5 of the provisional agenda

#### 1958 Agreement:

Consideration of draft amendments to existing UN Regulations submitted by GRVA

## **Proposal for a Supplement 3 to the 02 series of amendments to UN Regulation No. 131 (AEBS for heavy vehicles)**

### **Submitted by the Working Party on Automated/Autonomous and Connected Vehicles\***

The text reproduced below was adopted by the Working Party on Automated/Autonomous and Connected Vehicles (GRVA) at its twenty-second session (ECE/TRANS/WP.29/GRVA/22). It is based on GRVA-22-05 as reproduced in Annex III to the session report. It is submitted to the World Forum for Harmonization of Vehicle Regulations (WP.29) and to the Administrative Committee (AC.1) for consideration at their November 2025 sessions.

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\* In accordance with the programme of work of the Inland Transport Committee for 2025 as outlined in proposed programme budget for 2025 (A/79/6 (Sect. 20), table 20.6), the World Forum will develop, harmonize and update UN Regulations in order to enhance the performance of vehicles. The present document is submitted in conformity with that mandate.



*Add a new paragraph 6.11., to read:*

- “6.11. Virtual testing of dynamic tests
- 6.11.1. Virtual testing may be used by request of the vehicle manufacturer as an alternative for some of the tests described in paragraphs 6.4. to 6.6. The virtual testing shall be verified and validated according to Annex 4 and used in accordance with Annex 4.
- 6.11.2. Virtual testing may be used in the evaluation of the warning and activation tests in accordance with paragraph 1.8. of Schedule 3 and Schedule 8 of Revision 3 of the 1958 Agreement.
- 6.11.3. In order to demonstrate that the complete physical system can reliably deliver the required performance, at least 30 per cent\* of required tests shall be performed physically including at least one test of each scenario variant described in paragraphs 6.4 to 6.6 relevant for the approval. The tests to be performed shall be agreed between the manufacturer and Type Approval Authority or its Technical Service. Those tests already performed as part of the model validation, and corresponding to the vehicle type approval, can be considered as part of the 30 per cent of required tests.
- Footnote: \* The value of 30 per cent is considered as a first step for this regulation. It is expected that this value will be reduced in the future. Therefore, this value should be reviewed regularly in GRVA to take practical experience into account.
- 6.11.3.1. Notwithstanding paragraph 6.11.3, in the case of modification of the vehicle type and extension of the approval according to paragraph 7, the proportion of physical tests required to demonstrate that the complete physical system continues to reliably deliver the required performance, may be less than 30 per cent of the required tests and shall be agreed between the manufacturer and Type Approval Authority or its Technical Service.
- 6.11.4. Where virtual testing is used by the manufacturer, a separate report including at least the additional information specified in Annex 4 shall be annexed to the test report.”

*Insert a new Annex 4, to read:*

## **“Annex 4**

### **Virtual testing of dynamic tests**

0. Introduction (for information only)
- This annex describes the method that can be used to consider virtual testing as an alternative to physical testing, based on the manufacturer request.
- This method is mainly based on two separate activities:
- (a) Activity 1: The development, management, verification and validation of the toolchain; and,
  - (b) Activity 2: The use of virtual testing results to conduct testing required for approval process.
1. Definitions
- 1.1. “*Virtual testing*” is the process of testing a system using one or more simulation models.
- 1.2. “*Model*” is a description or representation of a system, entity, phenomenon, or process.
- 1.3. “*Toolchain*” is the combination of simulation model implementations as tools that emulate a vehicle function.

- 1.4. “*Validity domain*” is the domain of applicability of the toolchain.
2. Activity 1: The development, management, verification and validation of the toolchain
  - 2.1. General specifications
    - 2.1.1. Credibility of the toolchain that is used for the virtual testing shall be demonstrated by the vehicle manufacturer to the satisfaction of the Type Approval Authority or its Technical Service.  
For this, the following five criteria shall be considered:
      - (a) Capability – what the toolchain can do, and what the associated risks are;
      - (b) Accuracy – how well the toolchain reproduces the target data recorded in physical tests;
      - (c) Correctness – how sound and robust are the data and the algorithms in the tools;
      - (d) Fit for Purpose – how suitable the toolchain is for the assessment (e.g. vehicle dynamic model, sensor model, system control model, environment model, scenario model, targets model, ...) within its validity domain;
      - (e) Usability – The training and experience, which is needed and the quality of the processes that manage the toolchain’s use.
  - 2.2. Development of the virtual testing method
    - 2.2.1. Developing and using the toolchain is the responsibility of the vehicle manufacturer. The toolchain shall reflect the vehicle, system and components that are to be tested.
  - 2.3. Toolchain management  
The following information shall be provided by the manufacturer to the Technical Service:
    - 2.3.1. A description of the models and tools which constitute the toolchain and the method used to trace input data, parameters and output data back to the corresponding toolchain version.
    - 2.3.2. The processes which ensure that the personnel developing, testing and validating the toolchain and its components have appropriate experience, expertise, and training and evidence that these processes are implemented and effective. If there are any activities not directly controlled by the manufacturer, there must be an explanation of measures taken to ensure confidence in the quality and integrity of these activities.
    - 2.3.3. A description of the input parameters, along with any uncertainties in the model parameters, which have been used to validate the models included in the tools and toolchain. The manufacturer shall also provide documentation demonstrating that the data used to validate the models covers the intended scope and functionality of the toolchain.
    - 2.3.4. A description of the overall approach to data management.
    - 2.3.5. A description of the management activities which describe the modifications between toolchain releases, version control and the review processes to ensure those modifications result in a toolchain that is still suitable.
    - 2.3.6. Description and analysis of toolchain and components
      - 2.3.6.1. All parts of the toolchain, tools and models shall be described by the manufacturer.

- 2.3.6.2. The vehicle manufacturer shall define the validity domain on which the toolchain will be applicable and how the validity domain has been derived including any AEBS performance influencing factors, parameter ranges, assumptions, limitations and tolerances.
- 2.3.6.3. The documentation shall include a description of the key performance indicators which will be assessed during validation, such as time to collision, remaining distance or impact speed.
- 2.3.6.4. The documentation shall include a description of the accuracy requirements for the toolchain and its components, including comparison with physical tests.
- 2.3.6.5. The documentation of the toolchain shall include assumptions, limitations, uncertainties and the necessary levels of fidelity.
- 2.3.6.6. The manufacturer shall provide a description of the toolchain assessment methodology, including the impact of any errors and uncertainties on the results and the subsequent consequences for the compliance of the system with this regulation.
- 2.3.7. The manufacturer shall review the information produced in addressing the requirements of paragraph 2.3.6.2. and document any implications for the use of the toolchain.
- 2.4. Verification
  - 2.4.1. The toolchain and its components shall be capable of accurately representing the relevant aspects of the physical AEBS that is being modelled.
  - 2.4.2. The manufacturer shall provide documentation on the verification activity of the modelling that implements the AEBS function in the toolchain and its components. This shall include a description of the models, their implementation, how they represent the AEBS function and a description of the activities that have been performed to confirm that the models have been correctly implemented.
  - 2.4.3. The manufacturer shall provide an estimation of the numerical errors affecting the toolchain and its components and analysis that the errors remain sufficiently bounded.
  - 2.4.4. The manufacturer shall demonstrate the effect of variations of the model parameters on the output values and identification of the most critical parameters which will influence the results. This shall also include a robust calibration procedure for these parameters.
- 2.45. Validation
  - 2.5.1. The vehicle manufacturer shall describe their overall approach to validation including performance measures and a validation strategy. The validation strategy shall be agreed by the Type Approval Authority or its Technical Service, including physical tests performed to demonstrate that the toolchain is an accurate representation of the physical system. The tests performed shall ensure a statistical comparison between physical and simulation results is possible.
  - 2.5.2. The validation strategy shall be defined by the manufacturer and presented to the Type Approval Authority or its Technical Service for review and agreement.
  - 2.5.3. The manufacturer shall demonstrate how the toolchain achieves the key performance indicators defined in paragraph 2.3.6.3. and accuracy requirements defined in paragraph 2.3.6.4. This shall include justification for the choice of key performance indicators and accuracy requirements, and what the criteria is for satisfying these indicators and requirements.

- 2.5.4. The manufacturer shall provide the list of validation scenarios. The manufacturer shall provide the parameter descriptions and accuracy requirements that were needed to perform the validation tests.
- 2.5.5. The manufacturer shall provide documentation describing the validation that was performed to establish the credibility of the toolchain. This shall include information related to the processes that were followed, physical tests that were performed and models and tools that were used.
- 2.5.6. The manufacturer shall provide documentation that demonstrates how they have characterised the uncertainty in the input data and evaluated the model parameters. The overall uncertainty of the results shall be quantified based on the toolchain structure and from the data and its flow through the toolchain. This uncertainty quantification shall allow estimates of the likely errors and the required safety margins that shall be applied to the results when the toolchain is used for virtual testing.
- 2.5.7. At the request of the Type Approval Authority or its Technical Service, in addition to the documentation provided by the vehicle manufacturer, additional confirmatory validation, which shall include physical tests, shall be performed or witnessed. These tests may be relevant to the entire toolchain, specific parts of the toolchain or any of its components.
- 2.5.8. The number of physical tests shall be defined in agreement between the manufacturer and the Type Approval Authority or its Technical Service. They shall be sufficient to cover the validity domain specified by the vehicle manufacturer.
- 2.5.9. The methodology used to generate physical validation data, such as data recording equipment, data processing, calculation of scalar values shall be documented as part of the validation documentation.
3. Activity 2: The use of virtual testing results to conduct testing required for approval process
- 3.1. Compliance of the Advanced Emergency Braking System with the performance requirements as defined in paragraphs 5.2.1 to 5.2.2. of this Regulation may be demonstrated by the vehicle manufacturer to the Type Approval Authority or its Technical Service by making use of virtual testing of the dynamic manoeuvres described in the paragraph(s) 6.4. to 6.6. of this Regulation.
- 3.2. All virtual testing results provided by the manufacturer in applying for an approval in accordance with paragraph 4. of this regulation shall refer to the toolchain evaluated and validated according to paragraph 1. of this annex.
- 3.3. For each approval application the manufacturer shall provide a confirmation that the virtual testing:
- (a) Was conducted using a validated toolchain;
  - (b) Was performed by staff with appropriate competences and skills;
  - (c) Has been performing using by a toolchain that has a unique identifier and sufficient information including scope, regulatory applicability and validation history to ensure that there is traceability and assurance that the toolchain is suitable and fit for purpose; and
  - (d) Has been performed using a toolchain within its scope and in accordance with any restrictions.”
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